TRANSPORTATION POOLED FUND PROGRAM QUARTERLY PROGRESS REPORT

Lead Agency (FHWA or State DOT): _Missouri Department of Transportation_____

INSTRUCTIONS:

Project Managers and/or research project investigators should complete a quarterly progress report for each calendar quarter during which the projects are active. Please provide a project schedule status of the research activities tied to each task that is defined in the proposal; a percentage completion of each task; a concise discussion (2 or 3 sentences) of the current status, including accomplishments and problems encountered, if any. List all tasks, even if no work was done during this period.

Transportation Pooled Fund Program Project #	Transportation Pooled Fund Program - Report Period:		
TPF-5(395)	$\Box X$ Quarter 1 (January 1 – March 31)		
	□Quarter 2 (April 1 – June 30)		
	□Quarter 3 (July 1 – September 30)		
	□Quarter 4 (October 1 – December 31)		
Project Title: Traffic Disruption-free Bridge Inspection In	nitiative with Robotic Systems		

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Lead Agency Project ID:	Other Project ID (i.e., contract #):	Project Start Date:
S064101S	TR202004	August 1, 2019
Original Project End Date:	Current Project End Date:	Number of Extensions:
July 31, 2024	July 31, 2024	0

Project schedule status:

	$\Box X$	On schedule	\Box On revised schedule	☐ Ahead of schedule	Behind schedule
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Overall Project Statistics:

Total Project Budget	Total Cost to Date for Project	Percentage of Work Completed to Date
\$650,000	\$11,738	5.0%

Quarterly Project Statistics:

Total Project Expenses	Total Amount of Funds	Total Percentage of
and Percentage This Quarter	Expended This Quarter	Time Used to Date
\$11,738 and 2%	\$7,559	10%

Project Description:

Bridge inspection often requires the use of heavy lifting and access equipment, thus increasing operation time and direct costs. When access to the inspected area must be made from bridge decks, the indirect costs associated with road closure multiply. In such a case, travelers are frustrated with traffic congestion and, both the travelers and inspectors are subject to a safety concern on high volume highways. Moreover, visual inspection is quite subjective and often inconsistent. It is thus of economic, psychological and social importance to develop an alternative platform for faster, safer, cheaper, and consistent bridge inspection with minimum impact on traffic flow.

The INSPIRE University Transportation Center (<u>https://inspire-utc.mst.edu</u>) at Missouri University of Science and Technology has been focused on the development of advanced technologies to aid in bridge inspection and maintenance. Specifically, structural crawlers, unmanned aerial vehicles (UAVs), and multimodal unmanned vehicles will provide a mobile platform for in-depth inspection of elevated bridges. In particular, a special multimodal unmanned vehicle, named Bridge Inspection Robot Deployment Systems (BIRDS), will be developed to combine both the driving capabilities of crawlers and the flying capabilities of UAVs into one system for bridge inspection.

At the INSPIRE Center, microwave and hyperspectral images will be developed to assess concrete delamination and steel corrosion of reinforced concrete (RC) bridges. Together with other existing technologies such as impact echo, impact sounding, and infrared images, they will provide a suite of measurement tools and methods for the nondestructive evaluation (NDE) of structural damage and deterioration conditions in RC and steel bridges. Innovative sensors such as UAV-based smart rocks for scour monitoring, integrated point and distributed optical fiber systems for strain and corrosion monitoring, and coupled antenna systems for strain and crack monitoring will provide mission-critical data, such as the maximum scour depth, corrosion-induced steel mass loss, and live load induced strains in order to normalize the NDE data taken over time at spatially distributed points.

The goals of this pooled-fund initiative are to engage closely with several state Departments of Transportation (DOTs) in the early stage of technology development at the INSPIRE University Transportation Center, and leverage the center resources to develop case studies, protocols, and guidelines that can be adopted by state DOTs for bridge inspection without adversely impacting traffic. The initiative involves the integration, field demonstration and documentation of a robotic system of structural crawlers, UAVs, BIRDS, NDE devices, sensors, and data analytics. Depending on the interest of participating DOTs, the objectives of this initiative include, but are not limited to:

- Development of inspection/operation protocols for various types of bridges with the robotic system integrated into current practice.
- Comparison and correlation of bridge deck inspections from the top and bottom sides of decks to understand the reliability of traffic disruption-free bridge inspection from the underside of decks.
- Design and technical guidelines of measurement devices on a robotic platform for the detection of surface and internal damage/deterioration in structural elements, and for the change in lateral support of foundations.
- Data fusion and analytics of measurements taken from various imaging and sensing systems for consistency and reliability.
- Development of best practices on bridge inspection using the robotic system.

To achieve the above objectives, the following tasks are proposed:

- Bridge selection for manual and automated inspections. Develop a selection protocol of bridges that are appropriate for both manual visual inspection and automated NDE. Thus, the performance of robot-based NDE can be compared with the current practice of visual inspection. The main parameters considered in this selection include span length, bridge type, accessibility, and importance. For example, river-crossing bridges may be inspected in great depth with advanced technologies, while simple highway bridges with easy access may not require any robotic platform during inspection.
- 2. Operation of multimodal unmanned systems. Develop a field test facility (e.g., recreational vehicle for a three-person crew) of the robotic system, including the BIRDS equipped with two infrared cameras (e.g., dual-sensor FLIR DuoTM Pro) and one impact sounding/echo device for RC elements, and a structural crawler for other bridge elements. The inspection crew will consist of a research engineer in bridge inspection and maintenance, a research assistant professor in system integration and robotics, and a rotating graduate student intern.
- 3. Correlation of top and bottom deck inspections. Due to gravity, deterioration on the bottom surface (a safety issue) is more critical than that on the top surface (a serviceability concern). On the bottom side of a bridge deck, deterioration such as concrete cracking, concrete delamination, and reinforcement steel corrosion are easier to detect from underside of the deck. The detection results derived from inspections above and below the deck will be compared to understand their correlation or complementary nature.

- 4. NDE and sensing integration into visual inspection. Develop preliminary guidelines to test NDE devices, such as hyperspectral and microwave cameras, for surface mechanical and electrochemical features as well as internal corrosion condition of steel reinforcing bars in RC elements, and test in-line fiber optic sensors for simultaneous measurement of strain, temperature, and mass loss in cross section of the reinforcing bars. Normalize/calibrate the NDE test results with those of a few pre-installed fiber optic sensors in structural behavior assessment. All the detected deterioration with measurement data are compared with visual inspection results to understand and quantify the improvement in probability of detection compared to the current practice of inspection.
- 5. Case studies with a representative bridge inventory. Develop an inventory of geographically-distributed test bridges and conduct case studies to implement and demonstrate NDE devices and sensors for the detection of surface and internal damage and deterioration in structural elements, and implement and demonstrate UAV-based smart rocks with embedded magnets for the scour monitoring of bridges. Up to nine (9) highway bridges/year in three (3) age groups or one long-span bridge/year from each participating state will be tested starting in the 2nd year. Store and maintain curated data within six months of their collection at the Scholars' Mine of Missouri University of Science and Technology. Share the data with the INSPIRE University Transportation Center investigators and, upon approval of state DOTs, the public as appropriate.
- 6. Protocol and guideline modification. Evaluate and refine as needed the protocols and guidelines of field tests for disruption-free bridge inspections after three (3) years of field operation. Imaging and sensing data are fused together to improve the detectability of problem areas with reduced capacity. The test results and corresponding visual inspection results are evaluated and summarized in a mid-term report, based on the probability of detection for structural damage/ deterioration and the improvement of visual inspection practice of bridges.
- 7. Limited release of protocols, guidelines, and criteria. Conduct a beta version rollout of the protocols, guidelines, and performance criteria at the INSPIRE University Transportation Center and the Missouri Local Technical Assistance Program (LTAP) in 4th and 5th years. As part of this rollout, workshops on the workforce development with the developed protocols, guidelines, and field demonstration technologies are conducted. Upon request, in-house workshops are held at participating states once a year.
- 8. Final reporting and curation of main findings. Prepare and publish a final report on the protocols, guidelines, and performance criteria of field tests with the robotic system at the end of 5th year. Store and maintain curated data and the final report at the Scholars' Mine of Missouri University of Science and Technology. Share the data and the report with the INSPIRE University Transportation Center investigators and, upon approval of state DOTs, the public as appropriate.

The performance period of this project will be August 1, 2019, to July 31, 2024 for five years. Table 1 details the specific schedule of this project by year. The kickoff (K) meeting, mid-term (M) report, draft (D) report/deliverables, and final (F) report/deliverables are marked on the project schedule. The final report will be due by the contract termination date.

Teels		Year			
Task		2	3	4	5
1. Bridge selection for manual and automated inspections	K				
2. Operation of multimodal unmanned systems					
3. Correlation of top and bottom deck inspections					
4. NDE and sensing integration into visual inspection					
5. Case studies with a representative bridge inventory					
6. Protocol and guideline modification				Μ	
7. Limited release of protocols, guidelines, and criteria					
8. Final reporting and curation of main findings					D
Notes: Mid-term report due at the end of 3 years Draft report/deliverables due 60 days prior to F Final report/deliverables due by the contract	the contra		ninatic	on date	e

Table 1 Project Schedule by Year

Progress this Quarter (includes meetings, work plan status, contract status, significant progress, etc.): Between January 1 and March 31, 2020, the following activities took place: Steel-girder bridges in the state of New York, Virginia and Wisconsin, and prestressed concrete Task 1. girder bridges in Georgia, Texas, and California will be tested. In Missouri, both groups of girder bridges will be tested. A total of 27 bridges in three clusters have been selected for each participating state to select 9 bridges in three age groups out of the 27 bridges for field tests. In Missouri, a total of 18 bridges will be selected in three age groups. Specific bridges selected will be submitted to the participating states for final selection and approval after they have been reviewed by Federal Highway Administration. The fabrication of the second prototype of a BIRDS for combined flying and traversing capabilities Task 2. began. The finite element model of the hybrid unmanned vehicle was established to optimize the structural design of the vehicle and understand the aerodynamic stability s as the vehicle approaches a bridge girder. This understanding can help develop an effective and practical navigation strategy of the BIRDS in application, providing foundation for workforce training in vehicle operation. Other Efforts. Two finalists were selected to fil the associate research professor and research engineer positions. The associate research professor is specialized in robotics and system integration. The research engineer is specialized in civil engineering with some construction and inspection experience. Offer letters have been prepared but must be approved by the S&T administrator before they can be sent out due to the new hire freeze policy associated with the COVID-19 outbreak. Anticipated work next quarter:

During the next quarterly, the following activities are expected to take place:

Task 1. Participating DOTs will be contacted to finalize the representative bridges to be tested.

Task 2.The second prototype of a BIRDS for combined flying and traversing capabilities will continue to be
built and tested for improved operability. A recreational vehicle will be designed and procured as a
field test station at bridge sites.

Significant Results:

When selecting candidates for manual and automated inspections, many factors were considered to narrow a large pool of candidates present in the National Bridge Inventory (NBI). First, representative bridges must be owned and maintained by the participating state DOTs. Second, these bridges provide Highway and Highway-pedestrian service. Third, they are either steel-girder or prestressed-girder bridges in each state to provide a comprehensive study of bridge deterioration in three age groups. The division of the participating states into the two groupings was based on regional climate and its representation in the remaining bridge inventory. Specifically, the states of New York, Virginia, and Wisconsin were grouped with emphasis on the study of steel girder bridges while the states of California, Georgia, and Texas were grouped with emphasis on the study of prestressed concrete girder bridges. In each participating state, nine bridges in the same material group will be tested. In the state of Missouri, however, both steel girder and prestressed concrete girder bridges will be investigated, having nine bridges in both materials for a total of 18 bridges to be tested. The nine selected candidates for each material type will be further broken up into age groupings of 5-9 years, 10-14 years, and 15-20 years.

Circumstance affecting project or budget. (Please describe any challenges encountered or anticipated that might affect the completion of the project within the time, scope and fiscal constraints set forth in the agreement, along with recommended solutions to those problems).

This project was impacted by the COVID-19 to certain degree. At Missouri S&T, laboratories were closed to students on March 16, 2020. Since then, all experimental works stopped. Even computer access may become an issue due to high traffic on internet during the period of virus spread, which will impact any computationally intensive tasks that require special computers from a remote site. Both the laboratory and computer access issues will likely continue to the first part or most part of the summer semester, which will impact the progress during the next reporting period.

TPF Program Standard Quarterly Reporting Format – 7/2011

Potential Implementation:

Once the field mobile testing facility is developed, some of the advanced technologies developed at the INSPIRE UTC will be tested and demonstrated at bridge sites in participating states. In-house workshops will be organized, as requested, to transfer the advanced technologies to practicing engineers.